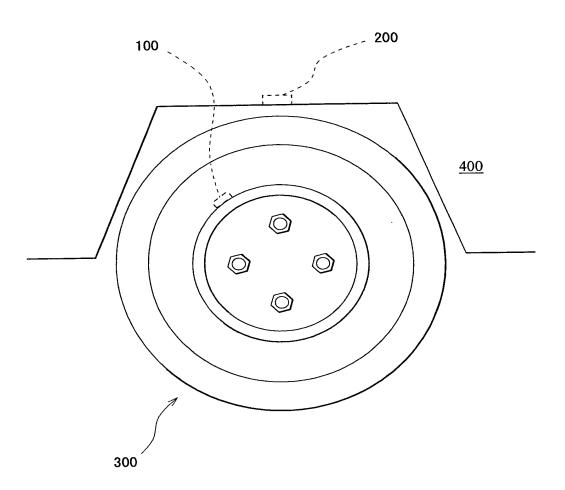


Fig. 2



*Fig.* 3

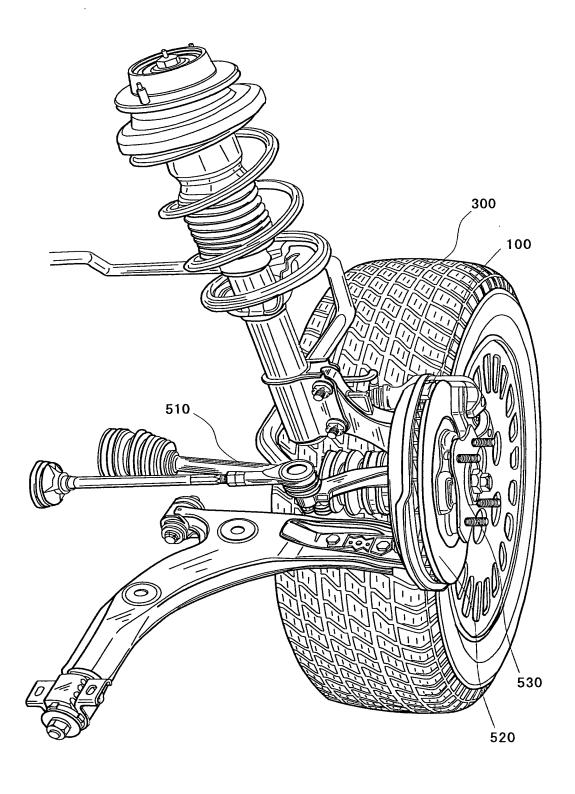
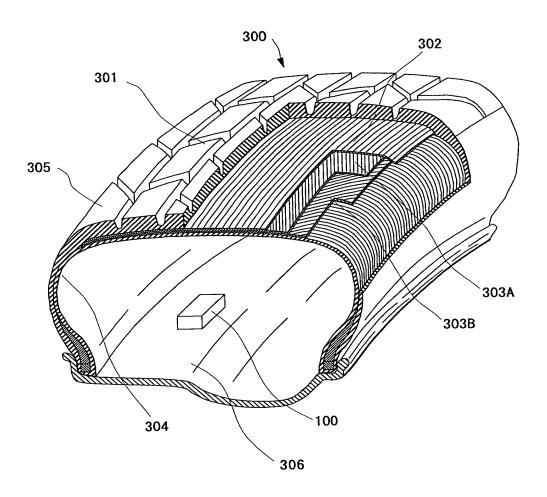


Fig. 4



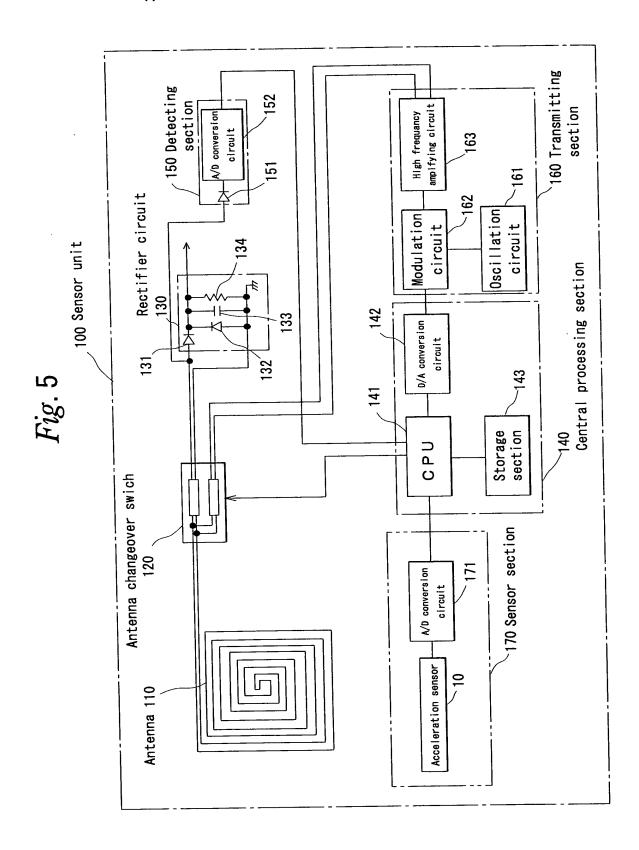
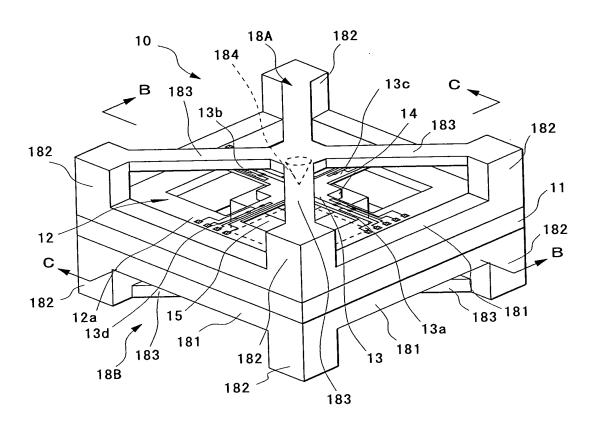


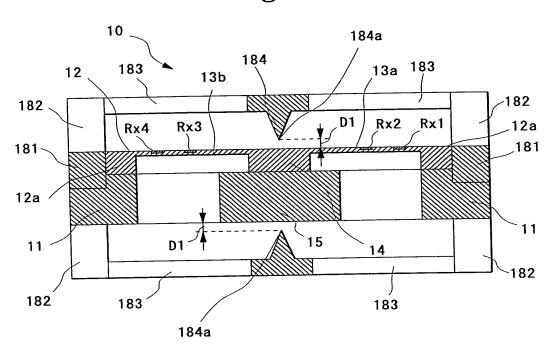
Fig. 6



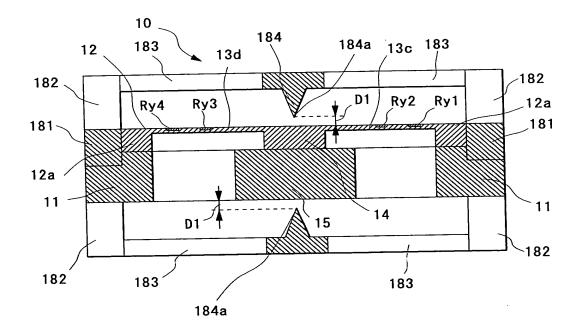
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*Fig.* 7



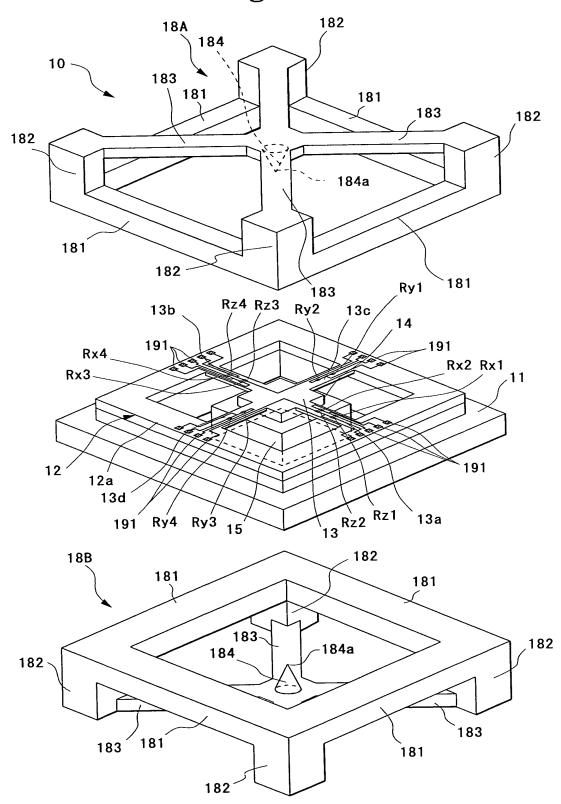
*Fig.* 8



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### Fig. 9



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Fig. 10

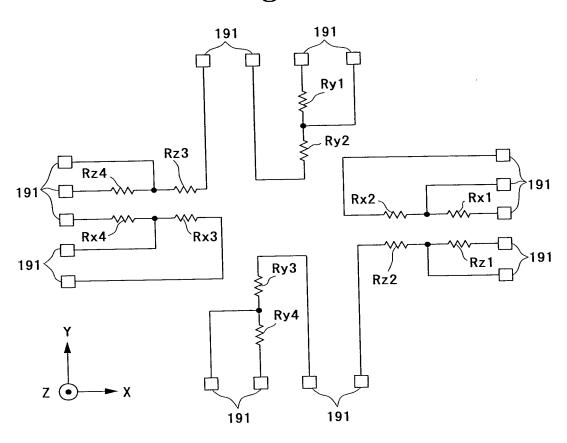


Fig. 11

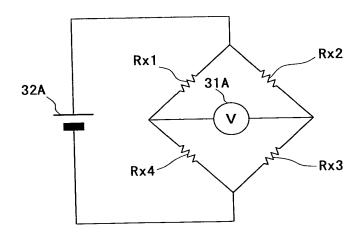


Fig. 12

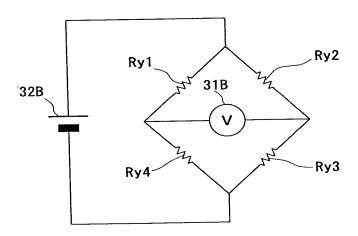
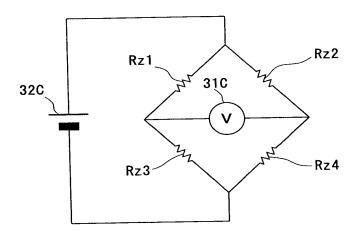


Fig. 13



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Fig. 14

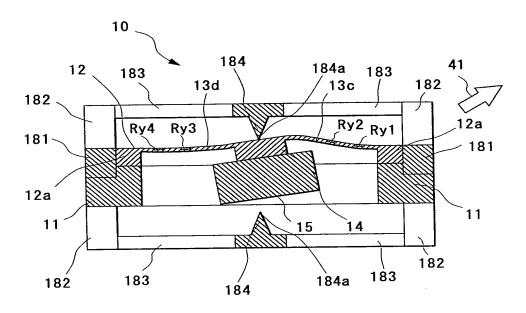


Fig. 15

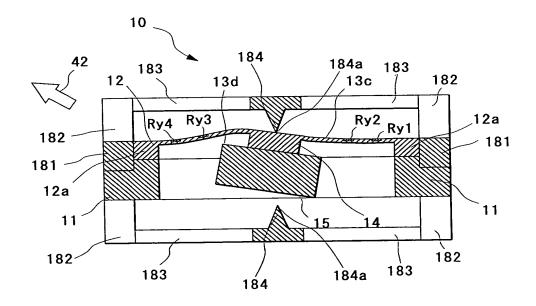
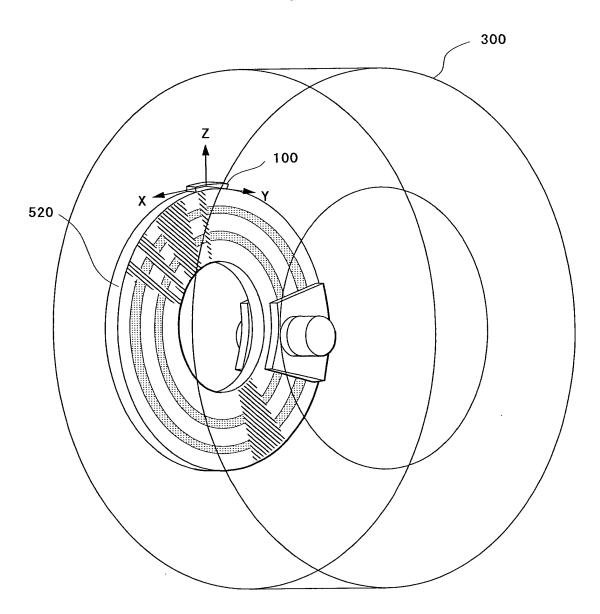
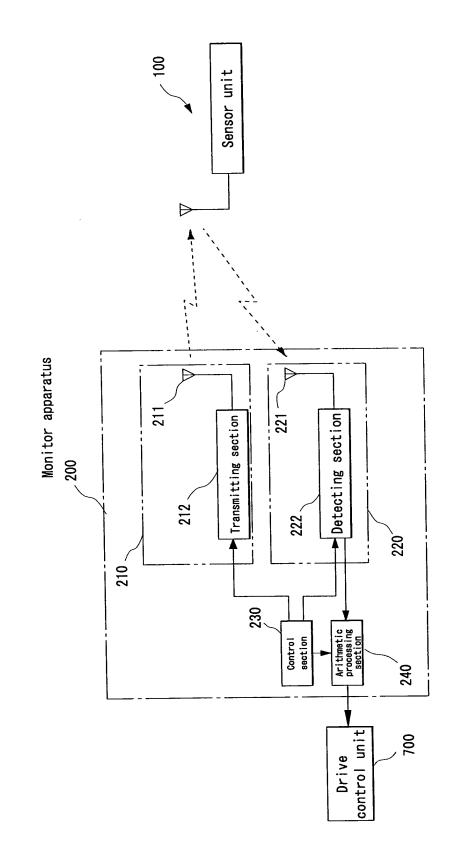
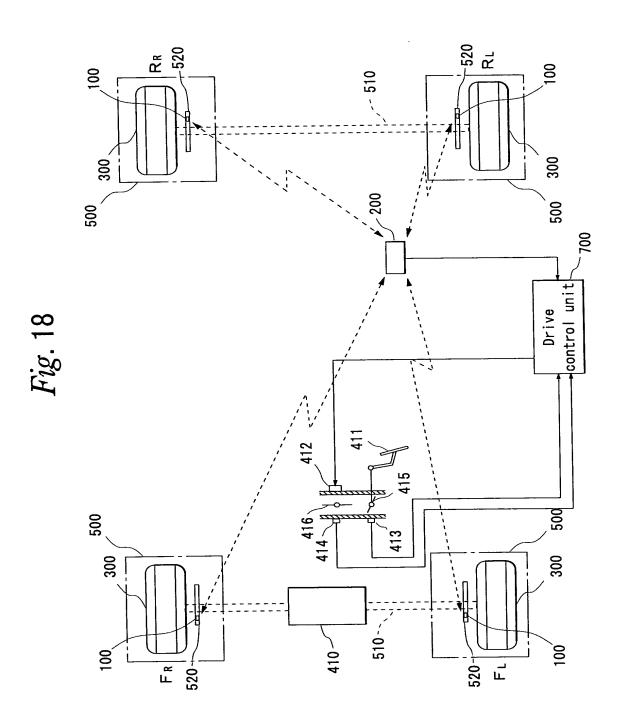


Fig. 16







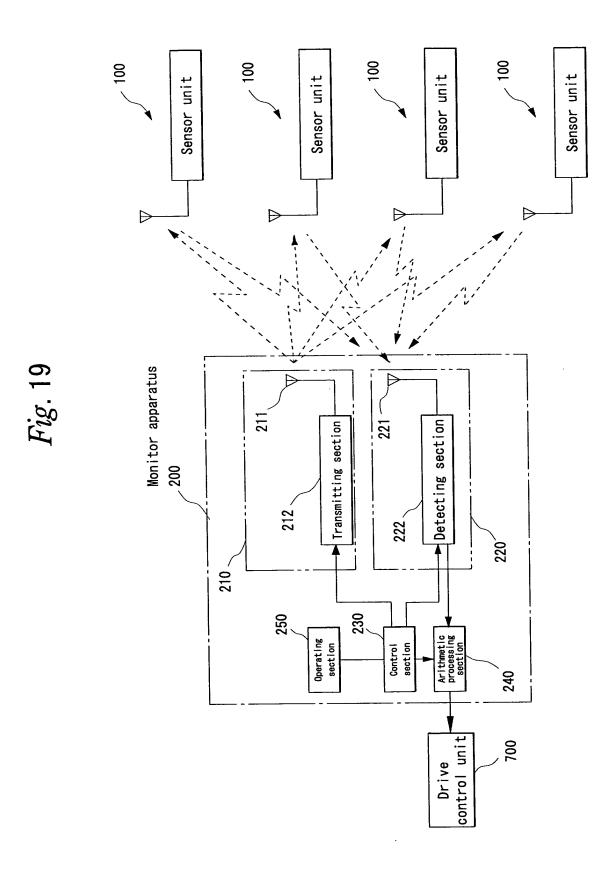


Fig. 20

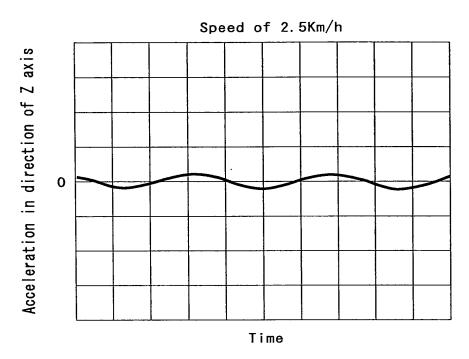
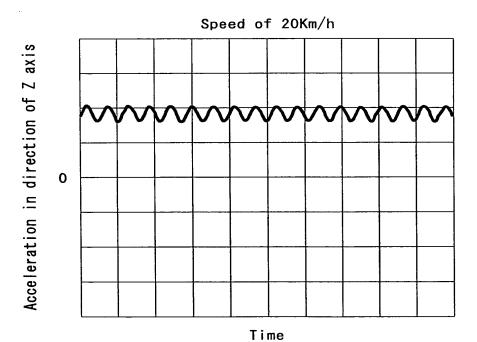


Fig. 21

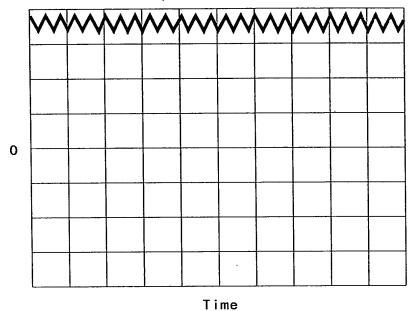


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Fig. 22

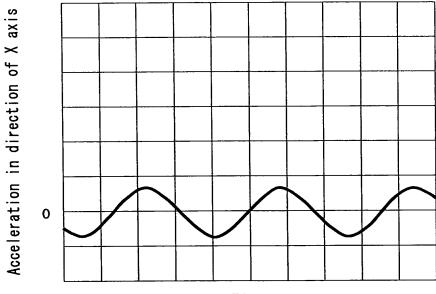
Speed of 40Km/h



Acceleration in direction of Z axis

Fig. 23

Speed of 2.5Km/h

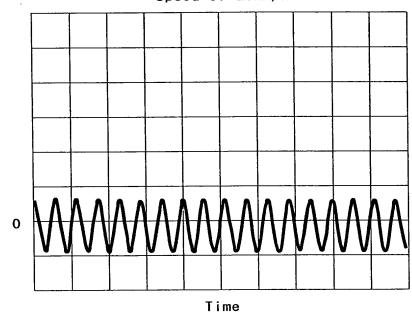


Time

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Fig. 24

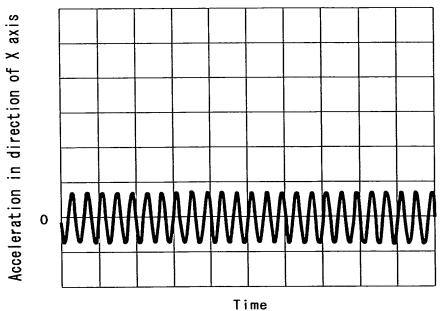
Speed of 20Km/h



Acceleration in direction of X axis

Fig. 25

Speed of 40Km/h



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Fig. 26

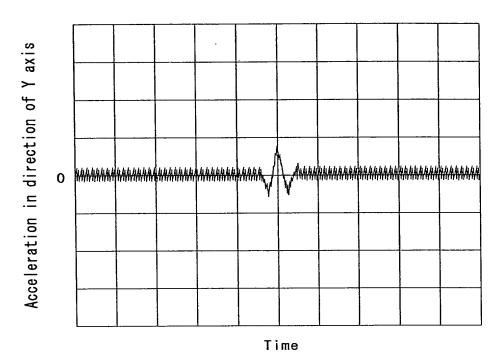


Fig. 27

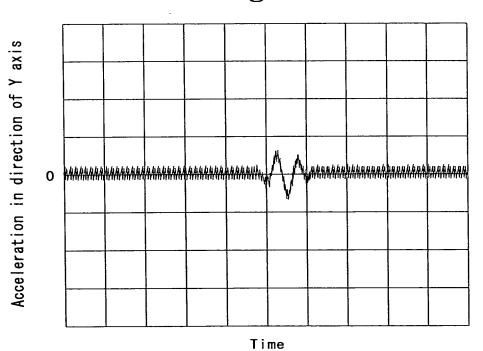


Fig. 28

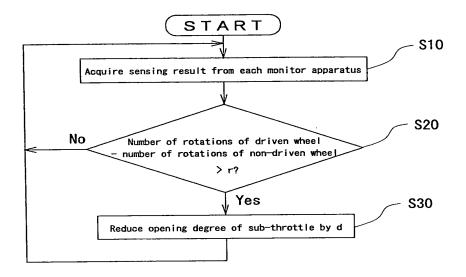
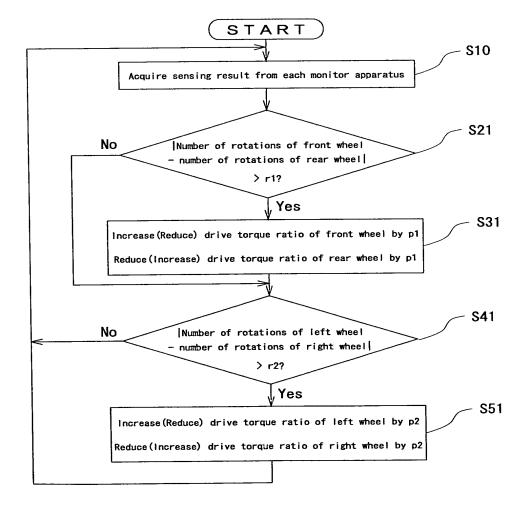
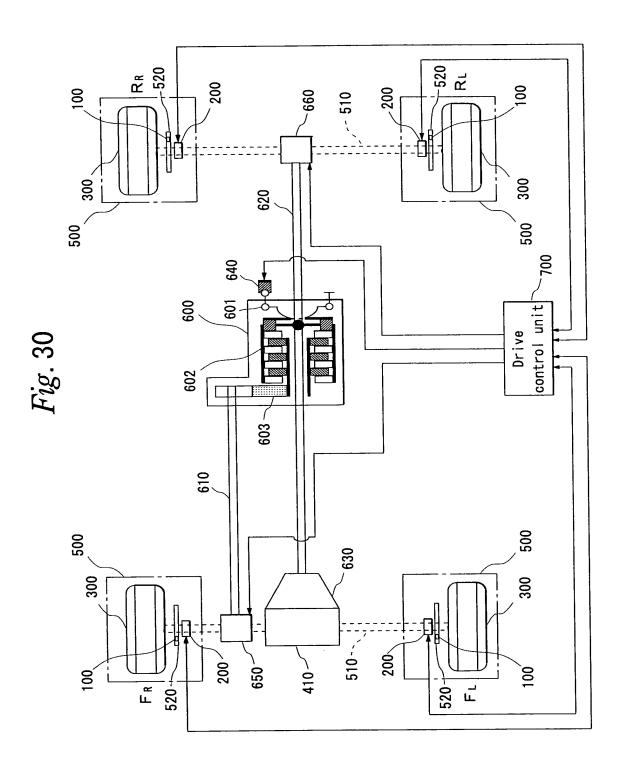


Fig. 29





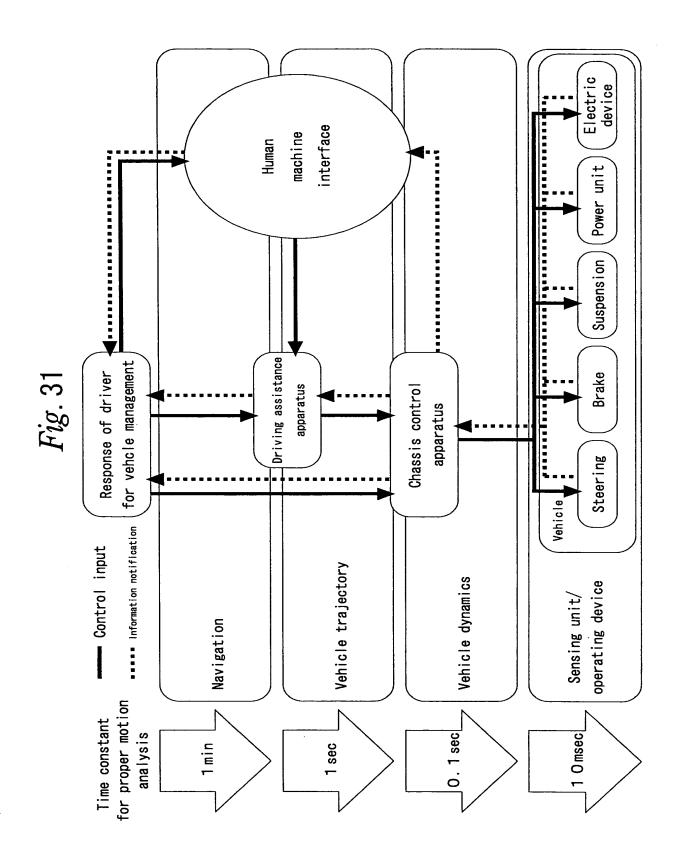


Fig. 32

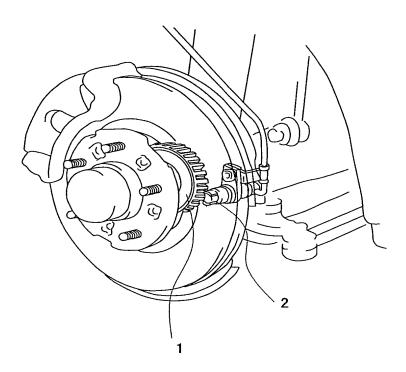


Fig. 33

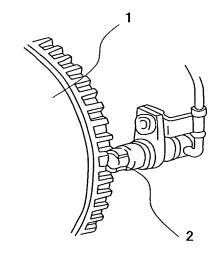
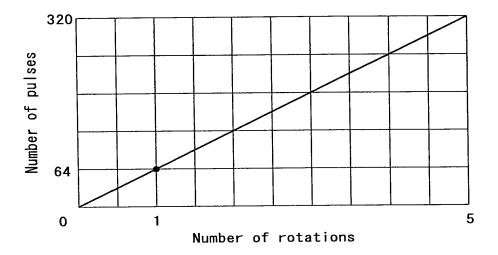
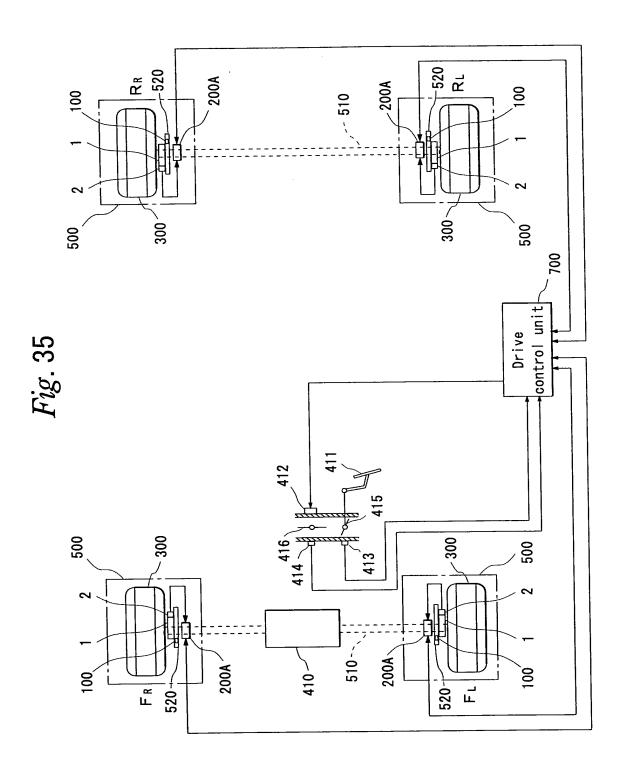


Fig. 34





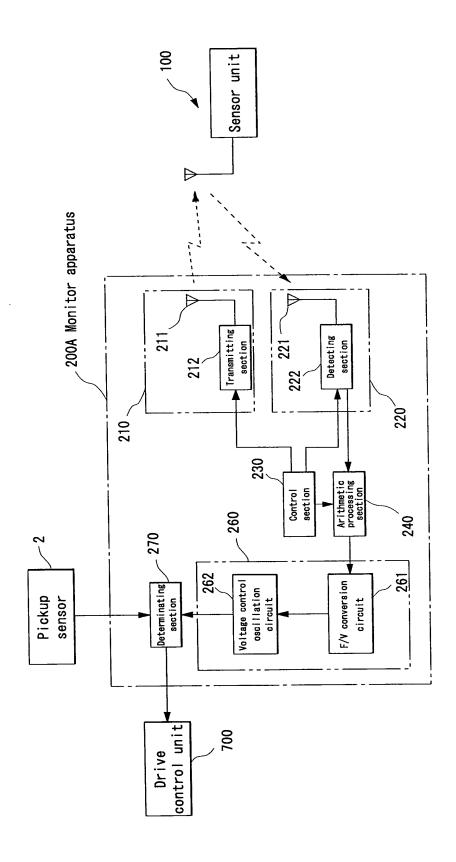


Fig. 36

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Fig. 37

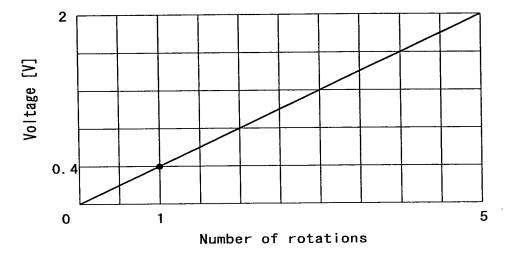
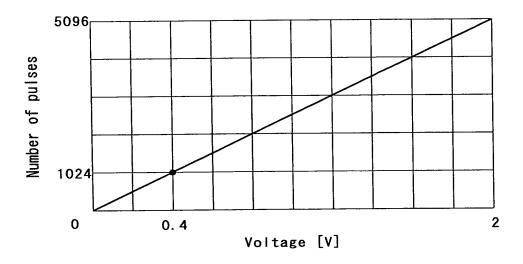


Fig. 38



TRACTION CONTROL SYSTEM AND SENSOR UNIT THEREOF HATTORI, Yutaka et al.

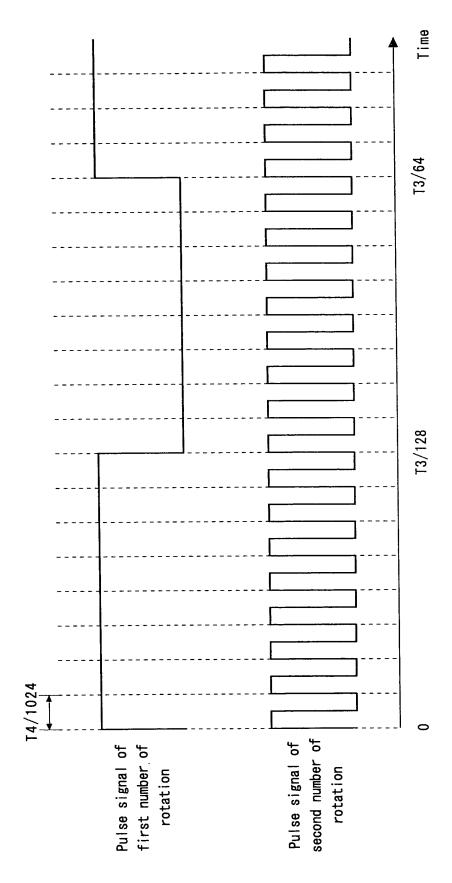


Fig. 39

HATTORI, Yutaka et al.

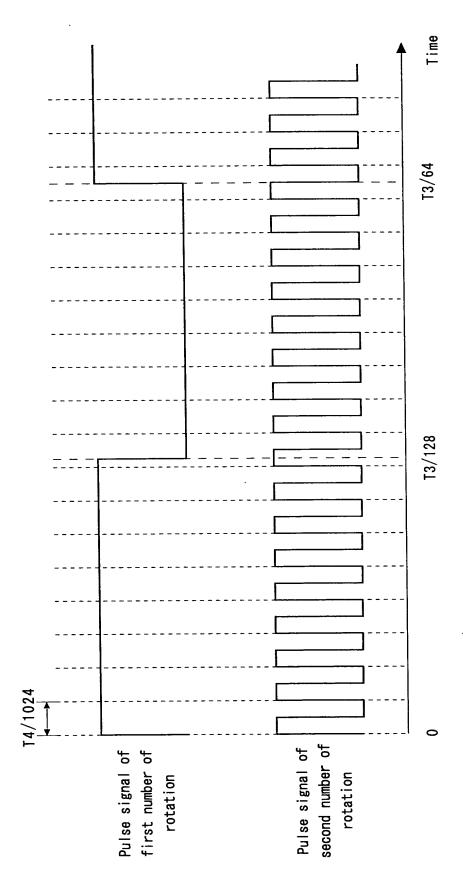


Fig. 40

TRACTION CONTROL SYSTEM AND SENSOR UNIT THEREOF HATTORI, Yutaka et al.

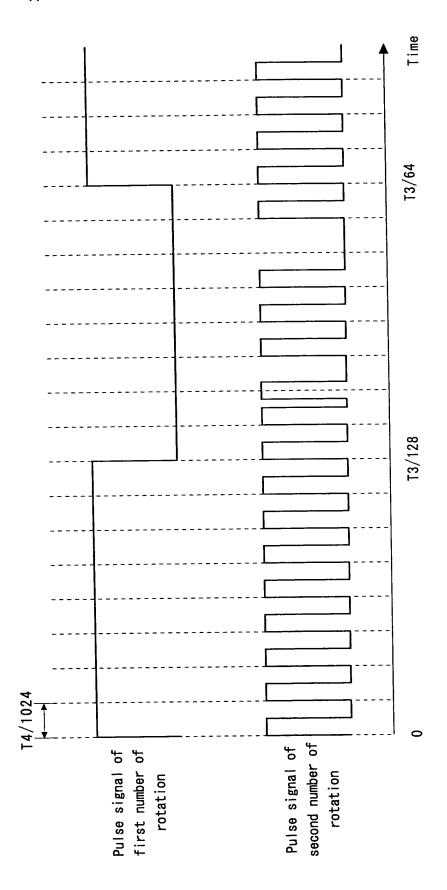
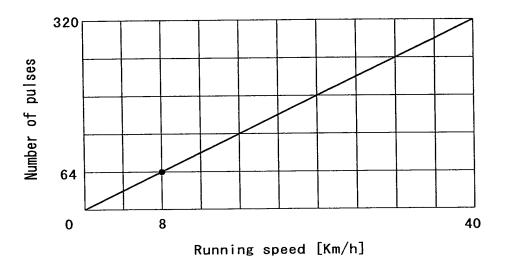
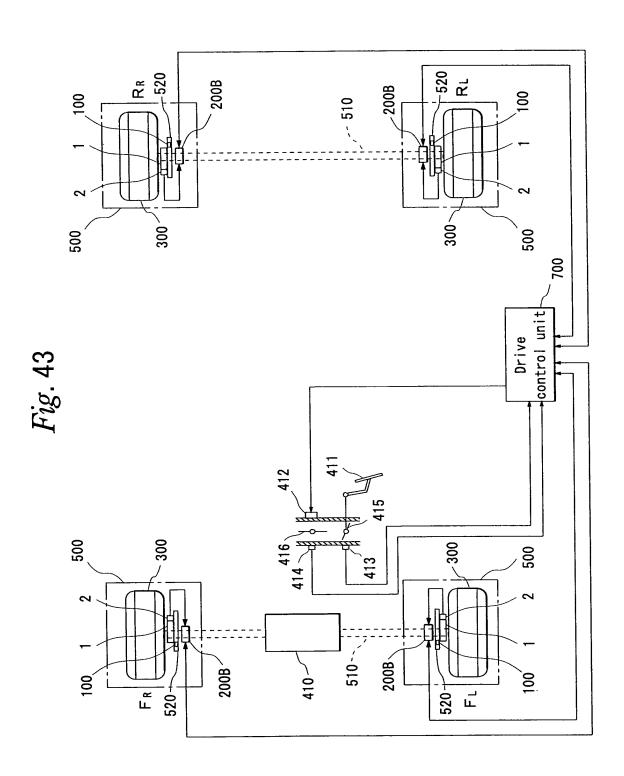


Fig. 41

Fig. 42





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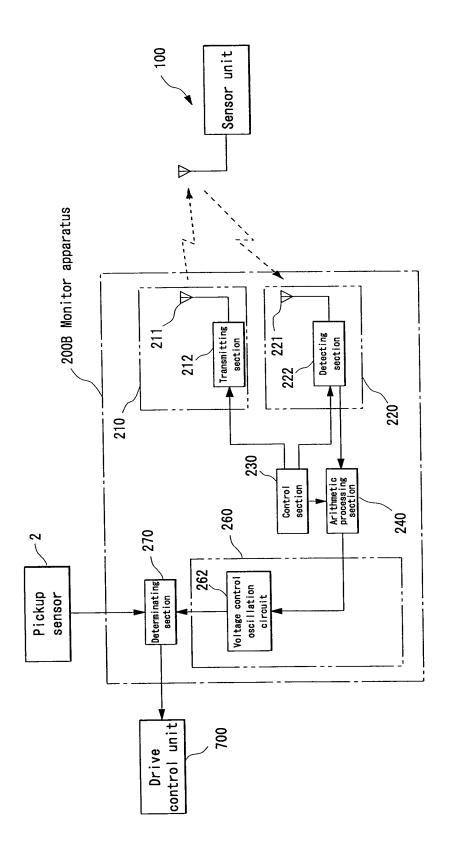


Fig. 44

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Fig. 45

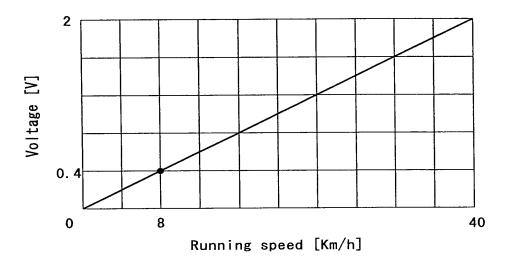


Fig. 46

